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EFFECTIVENESS ANALYSIS OF HYDRAULIC TORQUE WRENCH MACHINE USING FAILURE MODE AND EFFECT ANALYSIS (FMEA) AND LOGIC TREE ANALYSIS STUDY CASE ON HEAVY EQUIPMENT MANUFACTURING

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ABSTRACT

Production quality in terms of process efficiency and quality in the manufacturing industry must always be improved in order to maintain customer confidence. PT XYZ as a heavy equipment assembly company is one of the companies that depends on process reliability for a smooth production process. Based on this, the problems raised in this study focus on increasing the efficiency of the process of installing bolts on slew bearings. By using Overall Equipment Efficiency (OEE) and Process Capability (CpK) as the main benchmarks for measuring the quality of the production process where the latest data shows the average OEE value is at 18.53%, while the CpK value for the bolt tightening process is at 0,67. The OEE and CpK figures obtained show that the process quality is still not optimal and needs to be improved. The purpose of this research is to identify and prevent as many factors as possible that can lead to process failure. The methods used to evaluate processes and to identify where and how a process might fail are Failure Mode and Effect Analysis (FMEA) and Logic Tree Analysis (LTA). Both methods are used to identify and prevent as many factors as possible that can lead to a process failure. The results of research using the FMEA and LTA methods show that in the process of installing slew bearing bolts there is a process that needs to be improved because the RPN value is quite high, namely above 125. Some suggestions for improvement such as the use of a manipulator arm on a torque tool and the implementation of a manufacturing execution system (MES) can reduce the RPN value from above 125 to 28, where the process obtained is better than before.

Keywords: Failure and Mode Effect Analysis, Logic Tree Analysis, Overall Equipment Effectiveness, Process Capability, Production Process

1. Introduction

The manufacturing industry is one of Indonesia's largest connecting industries, according to data from the Ministry of Industry, the manufacturing sector's contribution to the national GDP in the second quarter of 2021 was 17.34%. With a demand of 4.5%, it should be noted that the MVA or Manufacturing Added Value for the Indonesian manufacturing industry is the highest among ASEAN nations. Meanwhile, Indonesian manufacturing is ranked ninth globally among all countries. According to Airlangga, Indonesia's manufacturing industry is the largest in ASEAN because Indonesia's economic system is a member of the one trillion-dollar club, which is distinct from that of other ASEAN nations (Kemenperin, 2021).

In the manufacturing industry, numerous processes are required to produce a final product that satisfies the needs of producers and consumers. Initially, everything is in the form of raw materials or parts supplied by suppliers, where it is unclear how the process will conclude. Next, they enter the production or assembly phase, which entails several processes before becoming finished goods or goods ready for distribution. Products are manufactured using empowered raw materials, components, and equipment. Typically, different products have varying quality levels. Occasionally, there are defective products among perfectly functioning products. When the rate of defective products sent to customers is excessive, the brand's image and reputation will suffer severely. It may reduce sales in the future. Consequently, it is natural to focus on the number of product defects to monitor the production process's quality.

Failure Mode and Effect Analysis (FMEA) is one method for minimizing the likelihood of product defects. FMEA is a step-by-step process for preventing these by identifying all

identifiable failures in the assembly, manufacturing, and design processes. In conclusion, it is a structured method for identifying the potential failure points of a process (breakdown) and how failure causes waste, defects, or adverse outcomes (effect) (Carlson, 2012).

The key to maximizing the benefits of FMEA lean manufacturing is its proper implementation and adherence to process findings consistently. It will result in significant manufacturing process improvements. In addition, FMEA reduces troubleshooting and downtime by identifying the causes of typical manufacturing process issues. This procedure is also beneficial to the design procedure. One of the most significant benefits of FMEA is the ability to gather information on how to address issues that disrupt business processes effectively. Then there are the tools used to determine the priority scale based on the Logic Tree Analysis (LTA) results of the FMEA analysis. The objective of preparing a Logic Tree Analysis (LTA) is to assign a priority to each damage mode and conduct reviews and functions, and function failures so that the status of the damage mode, a criticality analysis, and additional information are required.

Machining, fabrication, painting, and assembly are the four general stages of heavy equipment manufacturing. The overall machine assembly process is depicted in figure 1 (Nagane, 2002). Production scheduling traverse sequential flows through synchronized workstations based on the takt-time concept. Takt time is the amount of time available to complete tasks at a workstation to produce a single product. Each shop's production equipment is distinct. It requires using different internal production control systems and buffers in each shop. There are various buffer configurations possible. The relationship between pickup speed and cycle time, which influences production targets, is vital in a manufacturing environment.



Fig. 1. The Process Of Assembling Heavy Equipment In General

Sheet metal panels and raw steel are formed during the machining process. Typically, production here is conducted in batches. Due to the inherent nature of the process, this is necessary. It takes time to set up the machine, input the machine program, and place the fixtures and JIG during the machining process. In order to achieve economies of scale for these expensive machines, high-capacity engines are utilized. In addition, fabrication involves welding the parts formed during the machining process. Welding is a process that is typically performed manually or with a robot.

In the paint shop, the process is carried out in small batches based on the unit's color. When a color change is necessary, the spray gun must be cleaned. It causes a loss of both time and paint. It also increases the cost of treating environmentally hazardous paint components, such as diluents, prior to their release into the environment. A coating process for anti-rust is used in addition to painting.

The assembly shop is the final step in the process, where all the major parts are assembled to create a complete unit. The assembly process of the carbody in a hydraulic mining shovel involves the construction and integration of various components to form the main body structure of the machine. The carbody components, such as side frames, end frames, crossbeams, and other structural elements, are fabricated according to the design specifications. Steel plates and sections are cut, shaped, and welded together to form the main framework of the carbody. Carbody

bearings, which provide rotational support, are installed at strategic locations within the carbody structure. Pivot points, such as the swing bearing and slew ring, are mounted onto the carbody to enable the rotation of the upper structure. Electrical wiring harnesses, sensors, and control panels are installed and connected to enable communication between the carbody and the operator cabin. Control systems for operating the slewing motion, monitoring parameters, and safety features are integrated into the carbody. Once the carbody assembly is complete, a thorough inspection is conducted to ensure proper alignment, structural integrity, and component functionality.

Tightening bolts is a common process in the manufacturing of heavy equipment. The tightening process aims to achieve the correct clamp force for the joint to work and function properly. Correctly tightening bolts involves maximizing the bolts' elastic properties. For the bolt to function properly, it must behave like a spring. The tightening process applies axial pre-load stress to the bolt during operation. These stresses are equal and opposite to the compressive forces applied to the assembled components. It may also be called a "tension load" or a "tightening load".

The background of this research is to analyze and transmit a manufacturing process in the heavy equipment industry, where from the observations of researchers the process can still be improved and improved, Figure 2 shows a graph of the process capability of the screw tightening process on slew bearings.

From Figure 2 it shows that the process capability coefficient is still very low, which is around 0.56, and some processes are still out of standard so that it needs to be reprocessed which results in additional production time. Based on these data, it is necessary to make improvements to maintain quality and increase productivity.



Fig. 2. Process Capability Graph of Slew Bearing Assembly

One method to minimize the potential for product defects is to use Failure Mode and Effect Analysis (FMEA). FMEA is a step-by-step process for preventing things that can go wrong by identifying all foreseeable failures in the assembly, manufacturing, and design processes. In short, it is a structured approach to uncovering the possibilities where a process could fail (breakdown) and the ways in which that failure causes waste, defects, or harmful results (effects).

The overall key to getting the most out of FMEA lean manufacturing is its proper implementation and consistent adherence to process findings. This will lead to significant improvements in the manufacturing process. Additionally, FMEA reduces troubleshooting time and downtime by outlining the basis for common problems affecting manufacturing processes. This procedure also helps in the design process. One of the most significant advantages of FMEA is that it gathers information on how to effectively address issues that disrupt business processes. Then there are the tools used to determine the priority scale from the results of the FMEA analysis using the Logic Tree Analysis (LTA) method. The purpose of preparing a Logic Tree Analysis (LTA) is to give priority to each damage mode and carry out reviews and functions, function failures so that the status of the damage mode, criticality analysis and additional information is needed.

2. Literature Review

Failure Mode and Effect Analysis (FMEA) has emerged as a pivotal tool in the realm of manufacturing quality management. Previous works in machine tools analysis he failure modes can accurately represent real-world situations and thus assist engineers to formulate accurate improvement guidelines, thereby enhancing the robustness and lifecycle of machine tools (Lo et

al., 2019). Research by Mutlu and Altuntas (2019) an approach based on FMEA that integrates the advantages of the fault tree analysis (FTA) method and belief in fuzzy probability estimations of time (BIFPET) algorithm has been proposed in order to improve the performance of the FMEA method. The results of this study show that failure related to fabric trimming adjustment in the tenter has the highest risk priority number. The proposed approach can be used in various industry for risk analysis. In addition, results obtained by the study have indicated that the proposed approach can be implemented in practice to perform comprehensive risk assessment procedures as it reflects real-life dynamics to analyze and assess potential risk.

Research by Wang et al. (2019) presents a novel risk priority model for FMEA by using interval two-tuple linguistic variables and an integrated multicriteria decision-making (MCDM) method. The interval two-tuple linguistic variables are used to capture FMEA team members' diverse assessments on the risk of failure modes and the weights of risk factors. An integrated MCDM method based on regret theory and TODIM (an acronym in Portuguese for interactive MCDM) is developed to prioritize failure modes taking experts' psychological behaviors into account. Finally, an illustrative example regarding medical product development is included to verify the feasibility and effectiveness of the proposed FMEA. By comparing with other existing methods, the proposed linguistic FMEA approach is shown to be more advantageous in ranking failure modes under the uncertain and complex environment.

Implementing FMEA methods, leading to increased productivity and Overall Equipment Effectiveness (OEE) value in practical industry sector (Muthalib et al., 2020; Purwanto & Jaqin, 2021; Rozak et al., 2020). The study identifies the main factors contributing to low OEE values, such as reduced speed loss, idling and minor stoppages, and equipment failure. The output is improvement of overall equipment efficiency and reduce operational losses. Analyzing the Overall Equipment Effectiveness (OEE) and identify big losses is effective to develop corrective action plan and increase productivity and quality in the industry by implementing Total Productive Maintenance (TPM) and other maintenance strategies. The study by Hadisaputra and Hasibuan (2022) also reviews previous research on TPM implementation and its impact on equipment efficiency and productivity. The results offer valuable insights for improving machine maintenance and productivity at the factory (Saifuddin et al., 2022).

Research by Perico (2019) regarding the application of Manufacturing Execution Systems (MES) to support assistance and loss elimination processes in various industries. Perico found most current MES vendors have built lean functionality into their software, but a comprehensive methodology explaining how MES can be used to implement lean manufacturing is lacking. This research aims to fill this gap by presenting a lean-MES framework.

Research by Chen (2020) presents an approach for the creation of an automated Manufacturing Execution System (MES) according to the MDE concept that provides MES functionality relevant to the food and beverage manufacturing process. It consists of the necessary phases to complete the entire MES engineering process. Based on the application presented approach to the brewery brewing process, the feasibility and practicality of this approach were shown to be applicable. The research also identified areas for future work, such as considering real-time execution functions of MES, validation with real production data, and integration with shop floor control and enterprise management systems. Additionally, the need for expanding the range of predefined basic functions and enriching libraries with more modeling elements for different application domains in the food and beverage industry was highlighted.

Research by Mantravadi (2019) is to understand the development of manufacturing execution systems (MES) in the digital transformation era. The theoretical propositions made on MES (based on a survey of the literature) were examined empirically using three case studies in Danish companies. The findings provide an overview of Industry 4.0-ready MES and identification identified in future factories. This research also hides the current MES research related to Industry 4.0 into the key groups to be demonstrated in digital manufacturing.

From various references that have been questioned by the author. This study has the same focus on repairing and evaluating a manufacturing process in the industry using the Failure Mode and Effect Analysis (FMEA) method and logic tree analysis. In this study, the use of the FMEA and LTA methods was applied to the repair process in the heavy equipment assembly industry.

3. Research Methods

This This research was conducted to measure the effectiveness of the production process in order to provide recommendations for production machine maintenance planning as well as evaluations of various factors that can affect quality and process efficiency. Overall Equipment Effectiveness (OEE) is one of the methods used to assess the machine's efficiency. Comparing the value of machine availability (availability), work efficiency (performance efficiency), and product quality constitutes an OEE evaluation (quality rate). The Failure and Mode Effect Analysis (FMEA) method and logic tree analysis is also used to determine the various possible causes of process failure.

Many studies using FMEA as a risk analysis technique have shown successful implementation (Wessiani & Yoshio, 2017). Failure modes and effects analysis (FMEA) is one of the first highly structured systematic techniques for failure analysis (Tripathi & Jain, 2017). FMEA regulates the principle of identifying and prioritizing possible failures or defects (Shivakumar et al., 2015). In PFMEA risk quantification uses indicators (RPN), which are defined as the product of severity (S), incident (O), and failure detection (D) (Rachieru et al., 2013).

Determine corrective and preventative measures based on the various causes of the failure. This analysis uses RPN calculations to determine which failure rate is the highest. The RPN value is computed based on the relationship between variables, namely severity, failure detection, and frequency, which identifies risks that require corrective action.

Analysis and evaluation come next in the process. Based on the failure mode analysis, we can determine which items must be enhanced based on the priority scale. This enhancement factor can be analyzed using the 4M framework: man, method, material, and machine.

FMEA has been widely applied in several sectors. It is an effective tool for improving and analyzing system quality, and is applied in many industries such as machinery (Lo et al., 2019; Su et al., 2012; Baghery et al., 2018; Sakthivel & Ikua, 2017), electronics (Wang et al., 2018), chemical industry (Ahn et al., 2017), medicine (Liu et al., 2018; Wang et al, 2019) and Textiles (Mutlu & Altuntas, 2019; Altuntan & Kansu, 2019).

The Overall Equipment Effectiveness (OEE) value is calculated by multiplying the availability, performance, and quality rate.

$$OEE\left(_{0_{0}}\right) = Availabilityrate\left(_{0_{0}}\right)xPerformance\left(_{0_{0}}\right)xQualityrate\left(_{0_{0}}\right)$$

Availability is the availability of a machine/equipment, which is the ratio between the operating time and the loading time of a machine/equipment. Then the availability ratio can be calculated as follows:

$$Availability rate = \frac{Loading time - Downtime}{Loading time} x100_{\%}$$

Performance Rate is a benchmark for the performance efficiency of a machine that runs the production process. Then the performance efficiency can be calculated as follows:

$$Performance rate = \frac{Ideal cycle clinex Number of output}{Operating time} x100$$

OEE (Overall Equipment Effectiveness) is the gold standard for measuring manufacturing productivity. OEE can identify the proportion of production time that is truly productive. Production is said to be perfect if the OEE value reaches 100%. This indicates that the production has completed several elements such as: 100% quality (only good parts), 100% performance, and 100% availability without any downtime (Atmaja et al., 2018).

OEE as a best practice and standard was first introduced in the Total Productive Maintenance (TPM) framework (Nakajima, 1990). Applying multiple methods, such as different lean techniques, also increases OEE scores (Nguyen & Do, 2016; Antoniolli et al., 2017; Lam et al., 2016; Glass et al., 2016). Application of proper engineering methods, for example, the Method of Failure and Effects Analysis (FMEA), will also result in a higher OEE (Dobra & Josvai, 2021). Higher OEE can also be achieved by increasing the number of shifts in production, but by increasing the length of the shifts.

Overall Equipment Effectiveness (OEE) is a calculation used to determine the effectiveness of equipment. With this method, TPM seeks to maximize output by maintaining ideal operating conditions and equipment/machines running effectively. A tool that is damaged, slowed down, or

lacks precision and produces a defective product, the equipment/machine does not operate effectively. To achieve Overall Equipment Effectiveness, TPM works to eliminate six big losses which are heavy obstacles (Winatie et al., 2018).

3.1. Research Stages

Research stages are an explanation of the steps taken in research that describes the research process from start to finish so that the research is more focused and systematic. Figure 3 is a flow diagram of the research stages.

Collection and search of data is the initial stage of research which later this data is used for analysis to determine recommendations to improve the quality of the process. This study uses two types of data, namely primary data and secondary data.

Primary data is data that was first coined by researchers through effort and direct experience. Data collection was carried out through survey methods, observations, and direct interviews with relevant sources such as production operators, shopfloor section managers and maintenance technicians. Secondary data implies used information that has been collected and recorded by someone other than the user for some purpose. It is an available form of data that is collected from several sources. In this study using secondary data from the production, quality and also maintenance. This secondary data will later be used to calculate OEE and also process capability which will describe the quality and efficiency of the manufacturing process. This secondary data will be divided into 5 subgroups, with 30 data collection each.



Fig. 3. Research Process Flow

3.2. Data Evaluation and Planning Recommendations

From the results of data processing, analysis will be carried out to determine the OEE value, factors causing losses, and from Failure Mode and Effect Analysis to find out what main factors cause process failures. The results obtained will be used as material for improvements to the company and later in the form of recommendations for improvements to the company to increase the effectiveness of the process.

4. Results and Discussions

There were 30 samples collected for each production batch. Using a monitored pneumatic torque wrench, bolt-tightening data is recorded on the pump and extracted using a flash disk.

Quality Ratio

Quality ratio is a ratio that shows the ability of equipment to produce products that comply with standards. The data used in measuring this Quality ratio are output, reduced yield, and rework and reject. Table 1 below show the result of quality ratio of 5 subgroup samples of tightening bolt.

Subgroup	Output	Reject (NG Process)	Quality Ratio
Subgroup 1	30	0	100%
Subgroup 2	30	2	93,30%
Subgroup 3	30	1	96,70%
Subgroup 4	30	0	100%
Subgroup 5	30	0	100%

OEE Measurements

After the availability ratio, performance ratio, and quality ratio values are obtained, then the next step is to calculate the OEE value.



Fig. 4. OEE graphic

Table 2 - OEE								
Data	Availability	Performance	Quality	OEE				
January								
week 1	91,7%	22,3%	96,7%	19,7%				
week 2	90,7%	27,3%	96,7%	24,0%				
week 3	91,1%	18,1%	96,7%	16,0%				
week 4	90,1%	18,1%	96,7%	15,8%				
February								
week 1	86,0%	16,3%	96,7%	13,6%				
week 2	91,5%	18,3%	96,7%	16,2%				
week 3	90,6%	22,6%	96,7%	19,8%				
week 4	90,3%	23,0%	96,7%	20,1%				
March								
week 1	84,4%	24,6%	100,0%	20,7%				
week 2	90,5%	22,8%	100,0%	20,6%				
week 3	91,1%	18,3%	100,0%	16,7%				
week 4	90,6%	18,1%	100,0%	16,4%				
week 5	88,3%	17,8%	100,0%	15,7%				
April								
week 1	90,7%	27,6%	100,0%	25,0%				

week 2	87,0%	29,9%	100,0%	26,0%
week 3	91,1%	18,0%	100,0%	16,4%
week 4	90,7%	13,7%	100,0%	12,4%
Overall	89,79%	20,98%	98,45%	18,53%

From figure 4 and table 2 above, an average value of OEE obtained is 18.5%, which is still below the eligibility standard.

OEE Losses Analysis

It is beneficial, when measuring the value of losses, to identify losses such as equipment damage and hidden losses such as reduced speed. In this measurement, equipment failure losses are calculated by dividing the time between machine damage and repair by the machine's loading time.

 $Equipment failure losses = \frac{Failure time}{Loading time} x100_{\%}$

Defect Losss reflects how much time is available in the machine loading time that is absorbed to produce the product. By multiplying the total damaged by the Actual Cycle Time divided by the loading time of the hydraulic torque wrench machine.

 $Defectlosses = \frac{TotalrejectedxIdealcycletime}{Loadingtime} x100$ %

Reduced Yield is the loss of machine loading as a result of absorption of Cycle Time and Standard Time as a result of various things.

$$Reducedspeed = \frac{(Actualcycletime - Idealcycletime)xOutput}{Loadingtime} x100$$
%

Idle Minor Stoppage Losses are losses that absorb loading time but do not result in processing as a result of waiting for materials, or no processing at all. Minor idle time can also be an indication of optimal job balancing.

$$Idle \land Minorstoppage = \frac{(Target - Actual)xIdealcycletime}{Loadingtime} x100_{\%}$$

Cause and effect diagrams are used to make it easier to identify root causes to overcome Losses. It can be seen in table 3 that the loss value of 60% means that production efficiency is still low, and to find out the cause can be identified with a cause-and-effect diagram.

Table 5 - Losses analysis							
Losses type	Total Losses	% Losses	% Losses cumulative				
Equipment Failure	9,91%	16,49%	16,49%				
Defect	0,38%	0,63%	17,12%				
Reduce Speed	9,80%	16,31%	33,43%				
Iddle & Minor Stopage	40%	66,57%	100%				
TOTAL	60,09%	100%					



Fig. 5. Graph of value losses

Figure 6 shows a cause-and-effect diagram, and various factors, including lack of maintenance, operator misuse, and usage frequency, can cause equipment failure.



Fig. 6. Fault tree analysis OEE

Torque Data Characteristics Analysis

Torque data can describe the torque characteristics of the inner bearing bolt tightening. Table 4 displays statistical data for each subgroup.

Subgroup	Mid	Median	Range	Min	Max	Std Dev
Subgroup 1	1199,13	1192	58	1176	1234	15,99
Subgroup 2	1201,27	1201	74	1169	1243	20,24
Subgroup 3	1205,27	1206,5	75	1170	1245	18,35
Subgroup 4	1201,97	1201	73	1165	1238	17,91
Subgroup 5	1200,2	1196,5	88	1159	1247	23,24

Table 4 shows that the average torque required to install inner bearing bolts for subgroup 1 is 1199.13 Nm; subgroup 2 is 1201.27 Nm; subgroup 3 1205.27 Nm; subgroup 4 is 1201.97 Nm, and for subgroup 5 is 1200.2 Nm. The data presented in Table 4 is derived from the subgroup.

Then, use a control chart (X) to determine whether the inner bearing tightening process follows a particular pattern in each subgroup (1-5). Figure 7 shows that there are no sample data outside the control limits in the graph of subgroup 1, with an average torque value of 1199.13 Nm, the upper control limit being 1240 Nm, and the lower control limit is 1160 Nm. It is also known that the data graph lacks a discernible pattern, allowing it to be inferred that the mean process in subgroup 1 has been statistically controlled.

With an average torque value of 1201.27 Nm, the upper control limit is 1240 Nm, and the lower control limit is 1160 Nm; subgroup 2 data showed sample data outside the control limits. The data that exceeds the control limits are all within the upper control limits. The subgroup 2 sample data shows that process improvement is required to maintain the process statistically.

With an average torque value of 1205,27 Nm, Subgroup 3 data shows that data samples are outside the control limits. The upper control limit is 1240 Nm, and the lower control limit is 1160 Nm. The data that exceeds the control limits are all within the upper control limits. The sample data from subgroup 3 shows that process improvement is required to maintain the process statistically.

ith an average torque value of 1200.20 Nm, an upper control limit of 1240 Nm, and a lower control limit of 1160 Nm, Subgroup 5 data shows that sample data is out of control limits. The sample data from subgroup 5 shows that process improvement is required to maintain the process statistically.



Fig. 7. Control chart \acute{X}

Process Capability Index (CpK) Analysis

The data used for process capability is the result of tightening the inner bearing bolts in subgroup 1 – subgroup 5 are shown in Table 5 below.

Index	Subgroup 1	Subgroup 2	Subgroup 3	Subgroup 4	Subgroup 5	Average
Ср	0.83	0.66	0.73	0.74	0.57	0.71
СрК	0.82	0.64	0.63	0.71	0.57	0.67

Table 5 can be seen that in Subgroup 1-5 the average Cp value is 0.71 which is less than 1 so it can be said that the data is less homogeneous.

Failure Mode and Effect Analysis

Based on the data that has been obtained during the observation and has been analyzed, then it is necessary to find out which types of defects have the greatest risk to the production process and have the greatest impact on product quality. The cause of the problem with the greatest risk will later be made a priority for improvement by the company. One of the tools used to determine the causes of defects that have the greatest risk is FMEA (Failure Mode & Effect Analysis). FMEA is very useful for determining priority repairs for various causes of defects or failures in a product or process by calculating the RPN (Risk Priority Number) value. RPN is calculated by weighting with 3 aspects, namely Severity, Occurrence and Detection, so that the RPN (Risk Priority Number) value for each cause will be obtained. All stages of the inner bearing installation process are described in the FMEA check sheet with a total of 11 stages. Each stage describes all the potential damage that can arise during that stage and its impact. Each of these impacts has a severity, occurrence and detection value.

Table 6 - RPN Value for Each Stage of The Slew Bearing Bolt Tightening Process

	0	0	9
Process Step	RPN	Cum.	Cum%
Perform bolt tightening	616	616	49%
Turn on the vector pump and calibrate	336	952	76%
process of cleaning the surface of the carbody	72	1024	81%
Torque tightening equipment preparation	60	1084	86%
lubricate bolts with oil	48	1132	90%
Checking Material from Storage	32	1164	92%

Marking bolts after completion of fastening each bolt	28	1192	95%
Insert the bolt on the inner bearing	24	1216	97%
Check the completeness of the bolt material	16	1232	98%
Install hose on pump and tightening tool	16	1248	99%
Insert pins on inner bearings	12	1260	100%



Fig. 8. Pareto RPN Graph for Stages of Tightening Slew Bearing Bolts

No	Process	Failure Mode	Effect	Severity	Rootcause	Occur rence	Countermeasure	Detection	RPN
Checking 1 Material from Storage	Checking Material	Non- complia nt material	delayed process	1	No checking	4	Use of checksheets after material is supplied to the production line	2	8
	from Storage	there are material defects	Need to rework, longer time, delayed process	3	no inbound check quality	4	Quality checking in the inbound logistics area	2	24
	Check the	the number of bolts does not match	delayed process	1	No checking	4	Use of	2	8
2	completen ess of the bolt material	There are defectiv e bolt conditio ns such as misread	delayed process	1	no inbound check quality	4	Use of checksheets after material is supplied to the production line	2	8
3	The process of cleaning the surface of	Surfaces are not cleaned properly	There is contaminati on that can damage the thread	6	operator did not follow the procedure	4	Double check after lubrication process	2	48
	the Carbody &; slew ring then Apply sealant	Wrong use of sealant occurs	There is rust so that the components become brittle	6	operator did not follow the procedure	2	Use of Visual Control	2	24

4	lubricate bolts with oil	Bolts are not lubricate d properly	tightening is not smooth; torque is not appropriate and reduces clamp force	6	operator did not follow the procedure	4	Double check after lubrication process	2	48
5	Insert the bolt on the inner bearing, thread it by hand	mis thread bolt position	The tightening process is not suitable, the bolt may break	6	operator did not follow the procedure	2	Sampling for checking hand tighten	2	24
6	Insert pins on inner bearings	t pin position installati on	bearings cannot enter, delayed the process	3	operator did not follow the procedure	4	Added Visual Check	1	12
	Torque tightening equipment preparatio	Tooling selectio n errors	delayed process	1	operator did not follow the procedure	4		1	4
7	n: vector pump, hose, tightening tool and reaction bar	Not paying attention to tooling conditio ns properly	Damage occurs during the process, delayed process	7	operator did not follow the procedure	4	Added visual check for tooling used	2	56
8	Install hose on pump and tightening tool	Hose installati on is not tight	Torque calibration fails, delayed process low Torque, Reduced	2	operator did not follow the procedure	4	Use of Visual Control	2	16
9	Turn on the vector pump and calibrate	Torque value input error	Clamping Force and Can Reduce Component Lifetime Torque exceeds standard, bolts or components may be	7 7	operator did not follow the procedure	4	The use of system monitored tools, where the torque setting program has been prepared without the need to adjust torque by the assembler	6	168 168
		low torque	damaged Reduced clasp force, reducing component lifetime Bolts or	7	Misuse of tools	4	The use of a system of monitored tools, where the torque setting of the tool has been	6	168
10	Perform bolt tightening	over torque	components may be damaged	7	Misuse of tools	4	programmed and the addition of a control	6	168
	in cross order	wrong sequenc e	The clasp force is poorly distributed, reducing the lifetime of components	7	operator did not follow the procedure	4	barcoding or using an encoder, the addition of an arm manipulator structure, to produce a more consistent	10	280

						tightening process	
11	Marking bolts after completio n of fastening each bolt	no marking	customer feedback, reducing customer trust	7	operator did not 2 follow the 2 procedure	The use of monitored tools, with the recording of 2 data no longer requires manual marking	28

Improvement Plan

Design of the manipulator arm on the tightening tool

Utilizing the manipulator arm structure on the tightening tools is one of the improvements that can be made to increase the consistency of the bolt-tightening process. In the current process, the tightening tools are manually operated, moved, and held by the operator, which has the potential to result in inconsistencies in the reaction force required to withstand a torque of 1200 Nm. With the manipulator arm equipped with pneumatics, the operator needs less energy to move and hold the tools during the tightening process. In addition to improving process quality, a manipulator improves the operator's safety and ergonomics. This manipulator arm design has 3 degrees of freedom with dimensions tailored to the dimensions of the car body for multiple 2-station models. Figure 9 shows component details on the manipulator arm made from the material SUS304.



Fig. 9. Manipulator Arm Design

Structural strength analysis

A strength analysis of the manipulator's arm is performed to ensure that the design can meet the specified requirements (criteria). This calculation activity will concentrate on finite element modeling, analysis of stress and stiffness of structures, and a comprehensive analysis of strength and deflection aspects. Modeling and analysis of geometry utilizing the finite element method and ANSYS software. With the criteria of high strength and stiffness without permanent deformation under load. The manipulator's arm is made of SUS304 as its main material.



Fig. 10. Element model on ANSYS.

The load-induced stress value must not exceed the maximum allowable stress of the material. Where the allowable stress value is derived from the yield stress value of the material or is equal to 240 MPa.

Table 8 shows the results of the loading simulation. From the calculation of the construction strength using finite element analysis, it shows that the manipulator arm structure can support a vertical load of 500 kg from the object's mass and is declared safe, as the safety number is greater than one (SF> 1) and there is no critical point.

Table 8 - Loading simulation results							
Deflect	Safety Factor	Von Missa Strass	Material				
		Von Marses Stress	Allowable	stress	Yield	Material	Part
		IVIAX	(Mpa)		(Mpa)		
1,43	9,35	25,68	180		240	SUS 340	Base Reaction Arm
9,56	6,65	36,1	180		240	SUS 340	Stand Top Pipe
20,58	1,25	192,38	180		240	SUS 340	Upper Arm
22,12	0,66	363,11	180		240	SUS 340	Swing Arm
57,27	1,59	151,33	180		240	SUS 340	Arm 2
58,13	1,21	198,39	180		240	SUS 340	Arm 3
58,8	0,74	325,08	180		240	SUS 340	Up Down Hinge
63,58	4,43	54,22	180		240	SUS 340	Stand Tolls
8,56	0,67	357,61	180		240	SUS 340	Bushing Upper Arm



Fig. 11. Visualization of The Overall Deflection of The Manipulator Arm Structure

Torque wrench terminator using manufacturing execution system

In process evaluation using FMEA, one process step that needs to be improved in the inner bearing bolt tightening process is the system's ability to detect whether the torque applied to the bolt meets quality standards. There is no such system in the current process. When there is still a gap for the bolt-tightening process to pass through that does not meet quality, the torque value is checked at random.

Solving this issue requires an interlock mechanism where a system can detect whether the results of tightening the bolts are by quality standards. When a process deviates from the standard, the system can issue a warning and prevent the operator from proceeding with the following process: interlocking. After the interlock mechanism is added, Figure 12 shows the flow diagram. A manufacturing execution system is one of the technologies that can be utilized to implement the interlock system (MES). MES is a computerized system used in the manufacturing industry to track and document the transformation of raw materials into finished goods. The MES functions as a real-time monitoring system that enables control of various production process elements (e.g. inputs, personnel, machines and support services).



Fig. 12. Tightening Sequence After Integrated with Interlock System

It is necessary to use a control module on a torsion device that can transmit torque value data that MES can then process to implement the interlock system using MES. Therefore, the control module used must support an open protocol. The open protocol enables torque wrenches and other tools to interoperate without requiring a proprietary interface or gateway. The main benefit of using an open protocol is the ease with which features can be expanded to meet operational production requirements, in this case, the use of torque value data in interlock system applications. Figure 13 shows a schematic of MES-integrable torque equipment.



Fig. 13. The Main Frame of Monitored Torque System Using MES

Use of encoder to control sequence tightening

In the process evaluation using the previous FMEA, one of the process steps that need to be improved in the bolt tightening process on the inner bearing is how the bolt tightening sequence can be ensured according to the standard because no system can ensure that the process carried out has followed the procedure. There is no system capable of detecting when an operator makes a sequence error.

One system that can overcome this problem is to use an encoder in the design of the manipulator arm on each arm axis. In the manipulator arm design that has been designed, it has 3 degrees of freedom, so 3 encoders are needed to provide coordinate input signals to the system. Each encoder will later send information in the form of coordinates so that the system can determine whether the position of the tooling used is in the correct sequence. Rotary encoders provide a position feedback signal from a rotating shaft or object. They are available with analog (0-5V, 0-10V or 4-20mA) or digital outputs. Available resolutions range from 2.8° to 0.006°, thus providing accurate torque tool positioning. Figure 14 shows the position of the encoder and the shaft that is controlled on the manipulator arm.

The reference point is at the first process or at the first bolt which we consider to be position [0,0,0] or coordinates [encoder 1, encoder 2, encoder 3], then in a crossed sequence it is continued at the position of the bolt opposite it.



Fig. 14. Location of The Encoder On The Manipulator Arm



Fig. 15. Illustration of The Position of The Manipulator Arm and Encoder Relative To The Car Body This information will be used to command the system to ensure that each sequence adheres to a predetermined standard. This system is commonly referred to as interlocking. If an error in coordinates is detected during the fastening process, the system cannot continue the bolttightening process, or the torque tool cannot be operated. Figure 16 below illustrates the sequence and flow of the bolt-tightening process for clarity.



Fig. 16. Process Flow Sequence and Bolt Tightening

Logic Tree Analysis (LTA) Hydraulic Torque Wrench Machine

As a basis for determining how to handle failure modes that occur, LTA is a qualitative method that aims to classify failure modes into multiple categories. In general, the LTA process uses three structured questions (evident, safety, and category) to obtain categories of failure modes that occur, such as category A (failure modes affect safety), B (failure modes affect production), C (failure modes affect non-production), and D (failure modes affect non-production).

The new maintenance action is determined by the equipment's deterioration and conformity with the task selection based on the previously determined RPN value. Following a decision diagram to conduct a logic tree analysis is one of the methods for determining appropriate maintenance actions for failures.

The OEE loss analysis determined that equipment failure accounted for one of the largest losses. LTA can be used to reduce the occurrence of equipment failures, determine the proper action to be taken by the operator in the event of a failure, and assess the impact if the failure is likely to occur.

In Table 6, Evident is indicated as "YES" when the assembler or operator is aware of a system disturbance. The Safety column is marked with "YES" if the damage poses a safety risk and "NO" otherwise. The Outage column is marked with "YES" if this damage stops the engine and "NO" otherwise. The Category column has four entries: A (failure mode impacting safety), B (failure mode impacting production), C (failure mode impacting non-production), and D (hidden failure mode).

The process carried out at the Logic Tree Analysis stage with the RCM approach is to provide component categories based on the existing damage modes. The categories obtained with RCM are categories A and C with a percentage of 0% while B and D with a percentage of 75% and 25%.

Incorrect hose pur	ses <u>E</u> mp	S	0	
Incorrect hose pur	mp			
connection			Yes	В
Calibration failure The tool cannot operate There is a problem the pump cylinder resulting in less pressure	n with r Yes	No		
Incorrect hose pur connection	mp		No	В
Failure of tools to achieve target torque The results of the bolt in accordance with specifications	n with r Yes	No		
Damage to bolt th or threads Lack of oil	nreads			
The pump doesn't workDamage to electronic componentsBurnt motorThe condition of t brush is not good	the Yes	No	Yes	D
Torque tools locked on bolts (jamming)Shaft components on the tool can be damagedThe tool operates backward / in the wrong directionThe tool operates under a fixed object	Yes ed ect	No	No	В
Pump pressure is The linkage between the niston and drive plate is Seal	Yes	No	Yes	D
low broken Lack of oil				В
Valve damage	Yes	No	Yes	D
Leaking cylinders orcylinder is damaged Overheating occur	ITS Ves	No	Yes	В
tools Cylinder seal broken Oil that has never changed	been	110		
Overheat pumpDamage to pump componentsContinuous use w pauseOil that has never	been Yes	No	Yes	В

Table 9 - Logic	Tree Analysis	Using Torque	Wrench H	vdraulic Machines

Task Selection

Action selection is used to determine effective maintenance policies applied to minimize the likelihood of failure and cost-effective actions in terms of maintenance expenses. Failure mode that is directly related to Time Directed (TD), Condition Directed (CD), or Failure finding (FF) dictates the maintenance policy chosen.

Recommendations for actions produced with the Reliability Centered Maintenance (RCM) approach can be obtained based on the results of the selection of actions for failed components; namely, a percentage value of 12.5% is obtained in 1 component with Time Directed actions, a percentage value of 12.5% is obtained in 1 component with condition directed action, and a percentage value of 75% in 6 components with failure finding.

Table 10 - Torque Wrench Hydraulic Component Maintenance Policy					
Component	Failure Mode	Policy Task (RCM)	Information of Effectiveness		
Lubricant Filters	Damaged	Time Directed	Periodic maintenance and on- condition maintenance are forms of preventative maintenance that aim to replace a component or system at predetermined time intervals.		
Lubricant	Dirty, Diminish	Condition Directed	Preventive maintenance is performed based on specific conditions of a component or		

			system, with the goal of preventing damage. Due to the unpredictability of time variable		
Hydraulic Hoses	Broken or torn				
Quick Connector	Dirty, Damaged		Failure mode prevention by periodically checking a hidden function of the		
Cylinder Seals	Damaged				
Gauge Hydraulics	Filled with liquid,	Failure finding			
	accuracy failure		equipment		
Brushes	Wear out				
Couplings	Broken				

Discussion

The research showed that quality ratio of 5 subgroup samples of tightening bolt was 93,30% - 100%. Numerous variables, including the lubrication coat kinds, thread tolerance faults, and coefficient of friction, influence the ratio (Miao et al., 2020).

The average value of OEE obtained is 18.5%, which is still below the eligibility standard. Based on the described data for loading time and operation time, the biggest losses are caused by the inefficient use of available processing time, which results in 40% of idle losses and 40% of stoppages. The subsequent largest loss is 9.91% due to equipment failure. This is similar to research conducted by Rusman et al., (2019) to analyze OEE in a wood processing company, the main factors causing the low OEE value on the machine were the reduce speed factor, as well as the idle and minor stoppages.

By examining the average torque value in Table 4, it can be determined that the bolttightening results fall within the company's specifications. However, when the minimum and maximum values are considered, several processes fall outside the standard torque range of 1160 Nm to 1220 Nm. This indicates that there are still products that still need to meet quality standards.

The average Cpk value is 0.67 which also is less than 1.0, so the level of accuracy is low or the data does not meet the target. It can be concluded that the torque value on the inner bearing is not homogeneous and less accurate with respect to the specification value so that the process is not capable.

From the results of the RPN values and using the Pareto principle, there are 3 processes that are priorities for improvement, namely at stages 3, 9 and 10. In stage 3 of the car body and sealant cleaning process, here there is a potential for error if the cleaning process is not perfect and there is contamination on the threads, this can result in damage during the bolt tightening process. Another risk of damage, if the sealant is used incorrectly, is the potential for rust to arise which can affect the life of the components. In stage 9 of the calibration process and input of torque values. Here there is a potential for error when inputting the torque value setting and as a result the bolt tightening results may be out of quality standards. When the torque value goes outside the design standard limits, it will result in component damage, component life will be reduced, and machine performance, especially in the slew bearing section, can be disrupted, this will have an impact on customer confidence in the product produced. Apart from that, errors in inputting torque values are also difficult to detect. In stage 10, the torque tightening process must follow the cross sequence as described in sub-chapter 4.1. If this sequence is not followed, the clamp force will not be distributed evenly on the surface of the slew bearing and car body. As a result, the connection between the slew bearing structure and the car body is not optimal and this has an impact on component life and engine performance. This sequence error cannot be detected, because there is no system that is able to detect this tightening sequence. Stages 9 and 10 are the main priority for improvements to the inner bearing tightening process, because this process has the highest risk of damage and is difficult to detect when an error occurs in the process.

There are some improvements that can be made to increase the consistency of the bolttightening process such as: (1) utilizing the manipulator arm structure on the tightening tools to improves the operator's safety and ergonomics, (2) make a strength analysis of the manipulator's arm, (3) using Manufacturing Execution System (MES) to detect whether the torque applied to the bolt meets quality standard, (4) using an encoder in the design of the manipulator arm on each arm axis can be ensured the standard, (5) using Logic Tree Analysis (LTA) to reduce the occurrence of equipment failures, determine the proper action to be taken by the operator in the event of a failure, and assess the impact if the failure is likely to occur, and (6) task selection to determine effective maintenance policies applied to minimize the likelihood of failure and cost-effective actions in terms of maintenance expenses

5. Conclusion

Based on the results of data processing and analysis according to the findings of a study on the performance of the torque wrench hydraulic engine from January to April of 2022, the availability ratio is 89.8%, the performance ratio is 21%, the quality ratio is 98%, and the Overall Equipment Effectiveness (OEE) value is still low at 18.5%. Furthermore, based on the torque value data, the average Cp process capability is 0.70, and CpK is 0.67, which is still a low value. The FMEA analysis determined that a number of processes continue to have high RPN values, including activating and calibrating the vector pump and tightening the bolts. Using a Monitored Torque Wrench Utilizing a Manufacturing Execution System and a manipulator arm helps reduce RPN, resulting in improved process quality.

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